NEWSLETTER 01 | NOVEMBER 2026

Accept Remote



Welcome!

Welcome to the first edition of the AcceptRemote newsletter!

Launched in May 2026, AcceptRemote brings together 18 European partners to explore how remote operations can support the future of connected, cooperative and automated mobility (CCAM).

The project combines technological innovation with a strong focus on societal readiness, addressing questions of trust, safety, inclusiveness and acceptance. Its solutions will be developed and evaluated through three pilot demonstrations in Istanbul, Toulouse and Munich.

During the first six months, the consortium has focused on establishing the foundations for its research and aligning activities across the project's technical and societal dimensions.

In this issue, we introduce the project and its pilots, share highlights from our first consortium meetings, present our first scientific contributions, announce a project collaboration and list upcoming events.

We invite you to follow our progress!

The AcceptRemote Project Team

Remote mobility designed with society at its core

Remote operations can support the deployment of automated mobility services by enabling SAE Level 4 vehicles to be supervised and assisted from a distance. AcceptRemote investigates how these capabilities can be developed and integrated into future mobility systems while addressing the needs, expectations and concerns of users, operators and society. The project brings together technological development and Social Sciences and Humanities (SSH) research, with three complementary pilots providing real-world contexts for development and evaluation.

RideCare

Inclusive passenger mobility

RideCare will test remotely supervised shuttles in a dense urban environment, with particular attention to safety, trust, inclusion and the needs of vulnerable users. Two shuttles will provide last-mile passenger transport along Bağdat Street in Istanbul, with a focus on elderly people, young passengers and people with disabilities. The pilot will also explore how intuitive user interfaces and real-time operator support can contribute to safe and accessible mobility services.

LogiCare

Autonomous goods delivery

LogiCare will test autonomous delivery droids in a university campus environment and will investigate how one remote operator can safely supervise multiple droids. The demonstration will take place on the Rangueil campus in Toulouse, where the droids will be used for meal delivery. The pilot will examine the safety and operational requirements of remote supervision in a semi-controlled environment, providing insights into the potential for wider deployment of autonomous delivery services.

FlexiCare

Integrated passenger and freight mobility

FlexiCare will explore integrated passenger and freight mobility through city-scale simulation and real-world testing. At its centre is a Freight Consolidation Broker linked to delivery vehicles, which enables logistics providers to exchange and consolidate deliveries. The pilot will combine simulations of Munich's urban freight network with practical tests at the Mobility Innovation Campus in nearby Ottobrunn, where remote operators will supervise the vehicles. It will investigate how consolidating deliveries and coordinating them with passenger transport can optimise freight flows and make urban transport more efficient

AcceptRemote kicks off in Athens

6–7 May 2026 | Athens, Greece

The AcceptRemote consortium gathered in Athens for its Kick-off Meeting, marking the start of a three-year research collaboration. Partners introduced their planned activities, discussed the project's technical and societal objectives, and aligned their approaches to the three pilot demonstrations. Discussions covered key aspects of remote operations, including trust, communication reliability, scalability and user acceptance.

The meeting also addressed the foundations for project implementation, including pilot validation, communication and dissemination, data management and Open Science, as well as project coordination. These discussions helped establish a shared understanding of the project's priorities and next steps, laying the foundations for cooperation across the consortium.
Read more





First General Assembly in Bari

15–16 September 2026 | Bari, Italy

Hosted by Politecnico di Bari, the first AcceptRemote General Assembly brought consortium partners together to review progress and coordinate the next steps. The first day focused on activities across the project's work packages, covering societal and human factors alongside technical developments in system architecture, connectivity, AI-supported functions and human–machine interaction. Discussions also addressed how these activities would contribute to the three pilot demonstrations.

On the second day, two interactive workshops focused on stakeholder needs and expectations, and on pilot requirements and validation. Working in pilot-specific groups, partners explored the needs and concerns of different stakeholders, as well as the technical requirements, system components and workflows for each pilot. The workshops helped connect societal perspectives with technical development, supporting a shared understanding of the challenges and requirements of remote mobility operations.

Read more





AcceptRemote research presented at IIKI 2026

29 September – 2 October 2026 | Bled, Slovenia

Research on the assessment and monitoring of remote operators was presented at the International Conference on Identification, Information and Knowledge in the Internet of Things (IIKI 2026). Djibrilla Amadou Kountche from Akkodis presented the paper “An Interdisciplinary Approach for Training, Evaluating and Monitoring CCAM Remote Operators”, jointly developed by researchers from six AcceptRemote partner organisations: Akkodis, University of Ljubljana, Jožef Stefan Institute, Politecnico di Bari, Okan University and Otokar.

The work explores how physiological monitoring, behavioural observation, ergonomic assessment and human-centred interface design can be combined to better understand operator performance, cognitive workload, situational awareness and well-being. It also proposes a simulation-based training environment to support the training and evaluation of remote operators under different traffic and communication conditions. The findings are also relevant to AcceptRemote’s acceptance research related to how operators and users view new vehicle technologies.

Read more



Autonomous logistics at AIDI Summer School

8–11 September 2026 | Lecco, Italy

Bartolomeo Silvestri from Politecnico di Bari presented research on “Last-mile logistics with autonomous vehicles: best practices, strengths, and open research” at the XXXI AIDI “Francesco Turco” Summer School on Industrial Systems Engineering in Lecco, Italy.

The work draws on field experience from the IN2CCAM project, analysing demonstrations across its living labs to identify lessons learned, best practices and open research challenges for autonomous last-mile logistics. The presentation also highlighted how this experience could inform the planning and evaluation of AcceptRemote’s three pilot demonstrations – RideCare, LogiCare and FlexiCare.



Electric truck routing at IEEE SMC 2026

4–7 October 2026 | Bellevue, Washington, USA

Researchers from Politecnico di Bari, a partner in the AcceptRemote consortium, participated in the IEEE International Conference on Systems, Man and Cybernetics (SMC 2026). María del Cacho Estil-les presented the paper “Routing Electric Trucks on Electrified Highways: Impact of Battery Capacity on Optimal Routes”, co-authored with Bartolomeo Silvestri, Agostino Mangini and Maria Pia Fanti.

The study investigates how battery capacity affects optimal routing decisions for electric trucks using electrified highways, where vehicles can recharge while driving. The findings show how different battery capacities influence route selection and reliance on electrified road segments, contributing to ongoing research on sustainable transport and energy-efficient logistics. The findings are also relevant to AcceptRemote’s research on the acceptance new technologies, particularly how operators and end users perceive, trust, and respond to them.



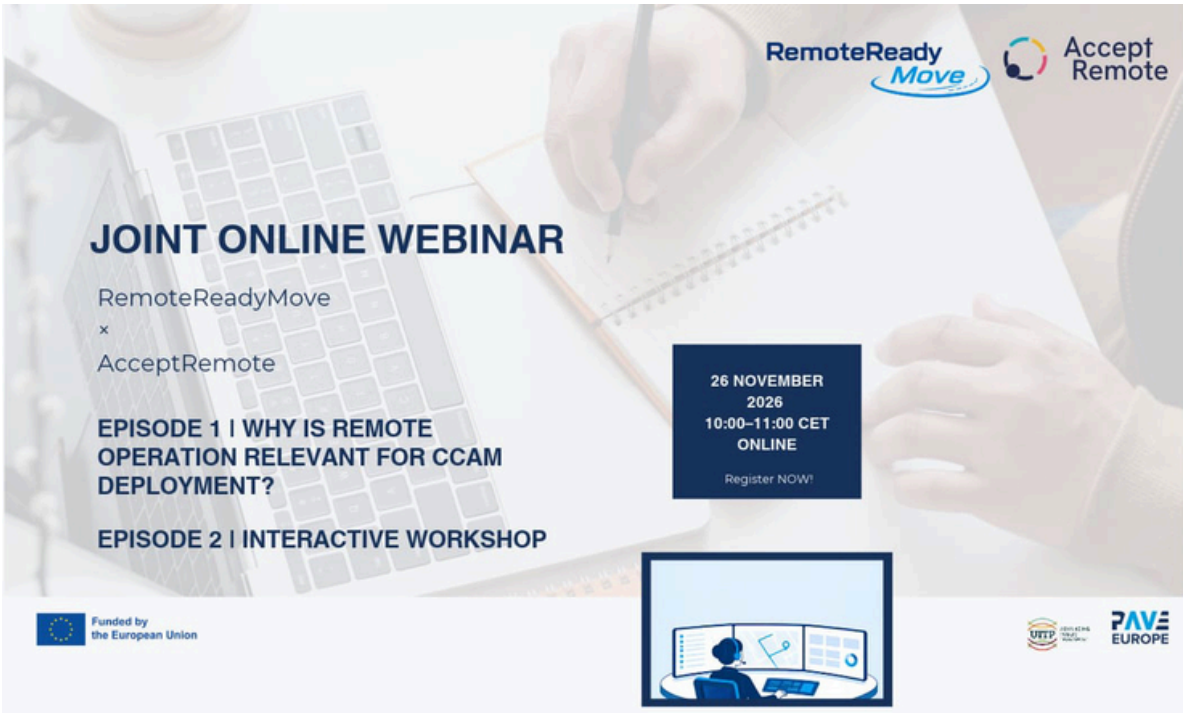
Collaboration with RemoteReadyMove

AcceptRemote has joined forces with RemoteReadyMove, a fellow Horizon Europe CCAM project running societal readiness pilots. By aligning their research and pilot activities, the two projects aim to prepare European society for the integration of automated mobility and remote operations.

The partnership builds on a longer history of cooperation between European CCAM projects. AcceptRemote itself grew out of earlier work by partners from the **CONDUCTOR** and **IN2CCAM** projects, who teamed up with new partners to tackle the challenges of remote operations and societal readiness. Working with **RemoteReadyMove** is the next step in this exchange of knowledge and experience.

The first joint activity is a webinar on 26 November 2026 on the role of remote operations in CCAM deployment. Participants will learn about both projects' approaches and use cases, see a practical example of remote operation and have the chance to ask questions. A joint workshop will follow on 7 December 2026, focusing on the operational and societal requirements for deploying remote operations in passenger and freight services. Both events are aimed at a broad range of stakeholders, including public authorities, transport and logistics operators, technology providers, researchers and organisations representing road users.

Register for the webinar



Upcoming events

November 2026 – April 2027

Explore upcoming events relevant to connected, cooperative and automated mobility, remote operations and societal readiness.

Date	Event	Location
16–18 November 2026	IRF 2026 Annual Conference	Geneva, Switzerland
17–18 November 2026	ALICE Logistics Innovation Summit 2026	Brussels, Belgium
18 November 2026	ReSKILLING Toolkit Workshop	Online
26 November 2026	Remote operations for CCAM - webinar	Online
1 December 2026	ReSKILLING – side event at POLIS 2026	Brussels, Belgium
2–3 December 2026	Annual POLIS Conference 2026	Brussels, Belgium
23–24 February 2027	RTR Conference 2027	Brussels, Belgium
16–18 March 2027	mobility move 2027	Berlin, Germany
16–18 March 2027	XPONENTIAL Europe 2027	Düsseldorf, Germany
18 March 2027	Autonomous Cities Summit 2027	London, UK

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